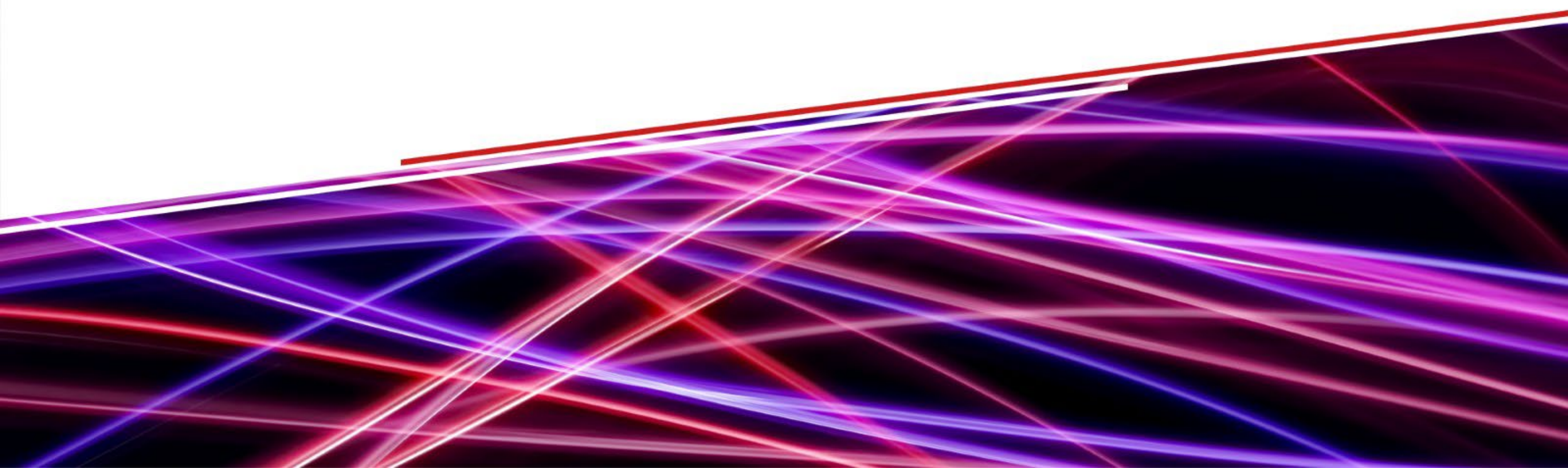


ACE 2024

Building a Digital Thread Discipline at Purdue

Travis Fuerst & Sathvik

Tuesday, March 4th, 2024



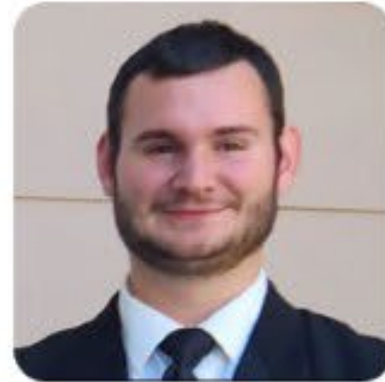
Introductions



Travis Fuerst
Professor of Practice
Purdue University
School of Engineering Technology
fuerstt@purdue.edu



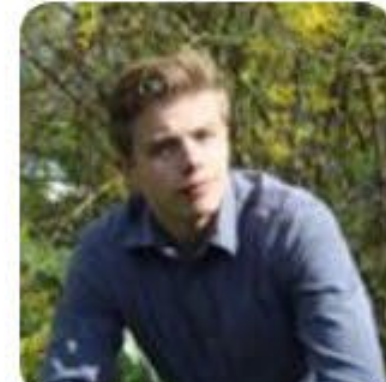
Sathvik Vudumula
Purdue University
Masters Student
svudumul@purdue.edu



John Koellisch
Major: Digital Enterprise Systems
DSP&T / Quarter Scale Tractor
jkoellis@purdue.edu



Evan Yoder
Major: Digital Enterprise Systems
Digital Systems Processes & Tools
yoder123@purdue.edu



Raymond Frazee
Major: Mechanical Engineering
Railside Robotics
rfrazee@purdue.edu



Manan Singh
Major: Robotics Engineering Technology
Railside Robotics
sing1145@purdue.edu



Jorge Varela
Major: Mechatronics Engineering
Purdue IEEE ROV
varela4@purdue.edu

Industry Advisors & Support

Industry Advisors and Support



SAIC



David Ewing Jr.

Jacob Donovan

Paul Hanlon

Hunter Erfman

Digital Engineering Director
M.B.A. - Krannert
BS – Mechanical Engineering
University of Buffalo / 1998

Digital Engineer
BS – Digital Enterprise Systems
Purdue University / May 2022

Director of Prod Dev
BS – Computer Science
Northeastern University/ 1986

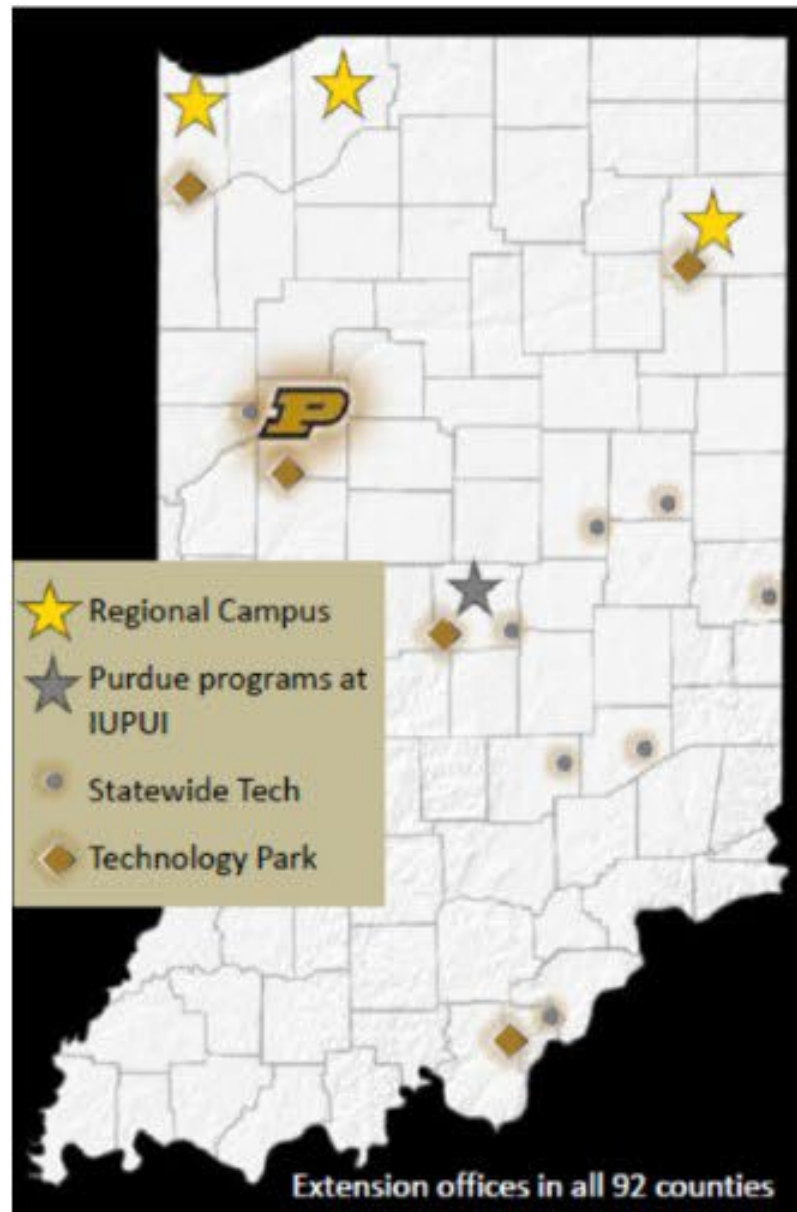
PLM Consultant
BS – Mechanical Eng Technology
University of Cincinnati

Purdue University



Introduction to Product Data Management

Indiana's Land-Grant University



Purdue West Lafayette

Fall 2022 enrollment = 50,884

| | |
|---------------|--------|
| Undergraduate | 37,949 |
| Graduate | 12,017 |
| Professional | 918 |

Purdue University Northwest

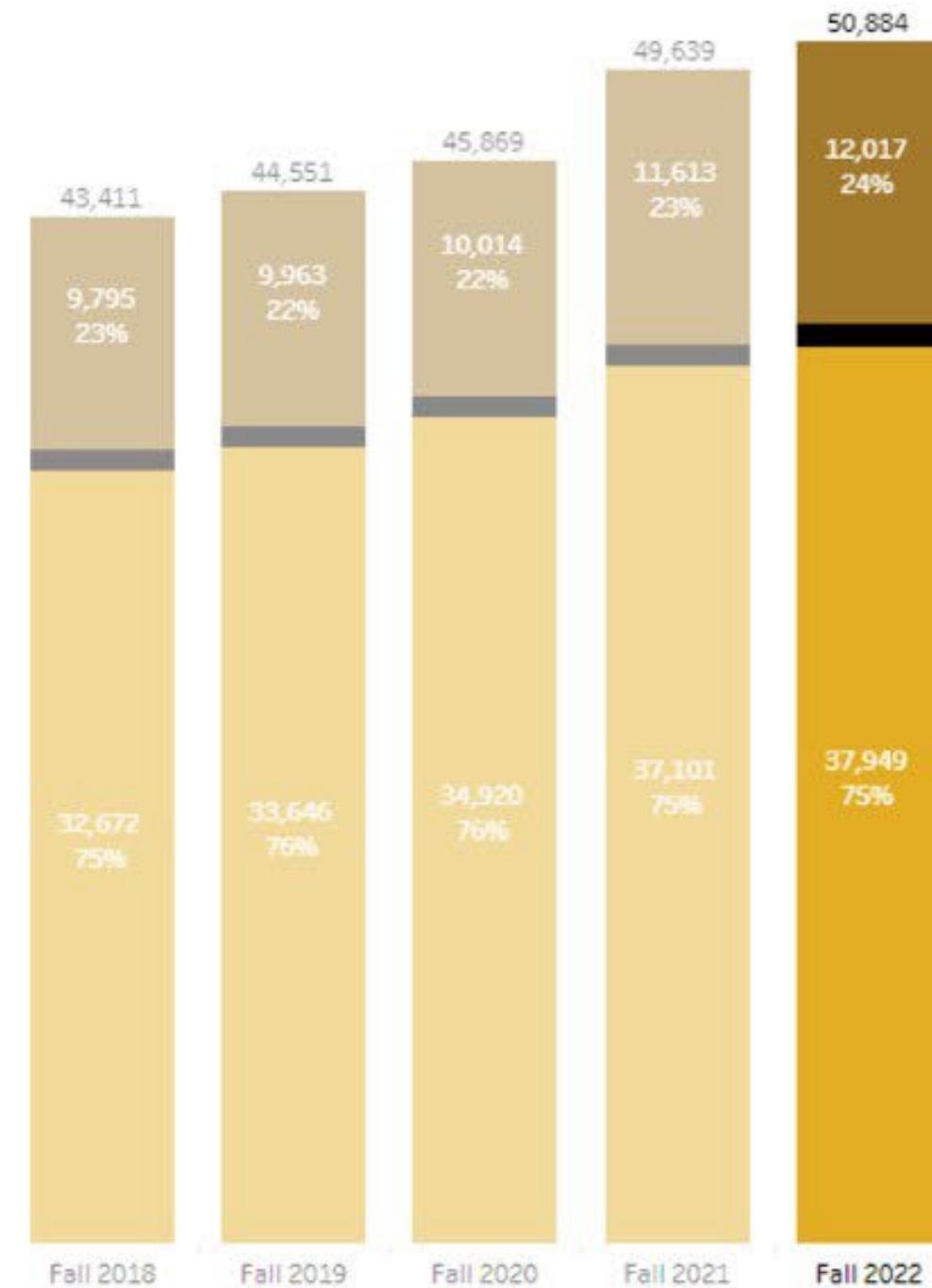
Fall 2022 enrollment = 8,911

Purdue University Fort Wayne

Fall 2022 enrollment = 9,069

Statewide Technology

Fall 2022 enrollment = 646



Purdue Colleges and Key Units



- Agriculture
- Education
- Engineering
- Health & Human Sciences
- Liberal Arts
- Krannert/Management
- Pharmacy
- Science
- **Purdue Polytechnic**
- Veterinary Medicine
- Libraries
- Honors College
- Graduate School

Purdue Polytechnic Institute

- Aviation and Transportation Technology
- Computer and Information Technology
- Computer Graphics Technology
- Construction Management Technology
- Division of Military Science and Technology
- **School of Engineering Technology**
- Technology Leadership and Innovation

Programs:

- Electrical Engineering Technology
- Industrial Engineering Technology
- **Manufacturing Engineering Technology**
- Mechanical Engineering Technology

Majors:

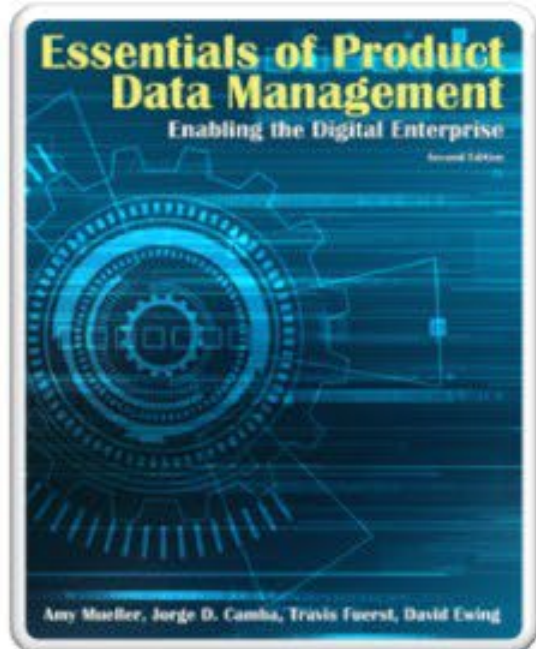
- Automation & Systems Integration Engineering Technology
- **Digital Enterprise Systems**
- Mechatronics Engineering Technology
- Robotics Engineering Technology
- Smart Manufacturing Industrial Informatics

Undergraduate Curriculum

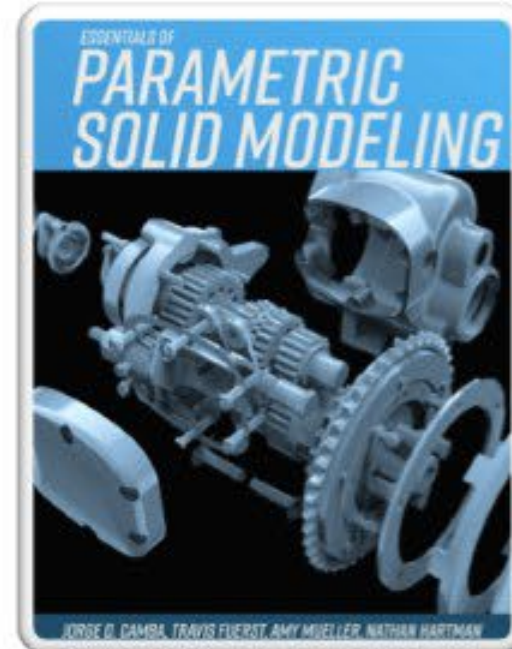
- PDM & Change Management in undergraduate Courses
 - MFET 10301 - Geometric Modeling Applications (~300 Students)
 - MFET 16300 – Graphic Communication & Spatial Analysis (~1200 Students)
 - MFET 11301 – Product Data Management (~30 Students)
 - MFET 20301 – Model Based Definition (~20 Students)
 - MFET 31301 – Business of Managing Product Data (~20 Students)



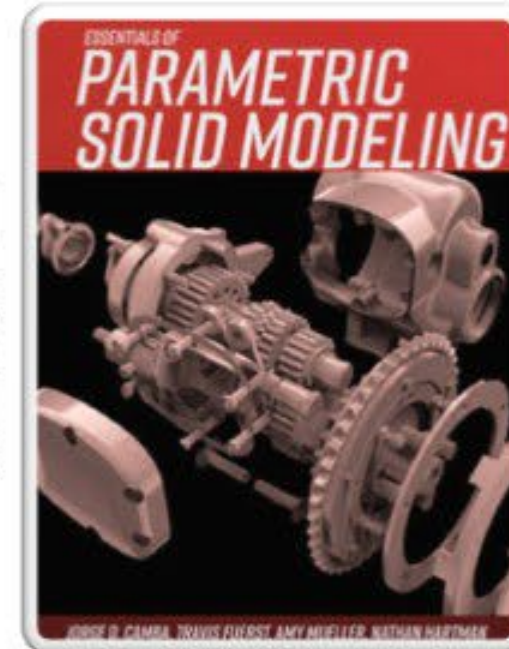
The CM2 Approach to Change & Config Mgmt



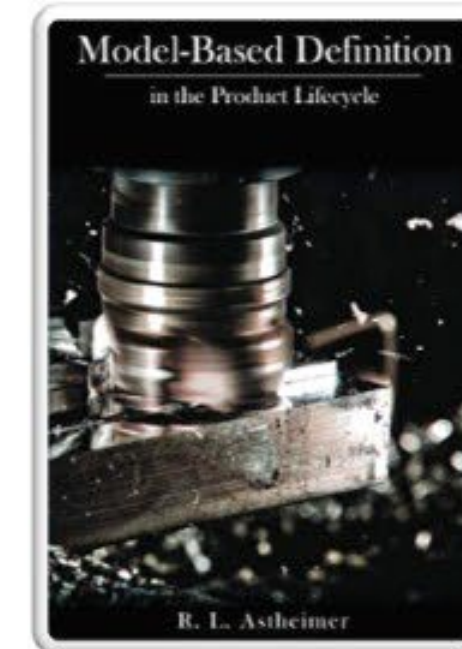
Essentials of PDM



Essentials of Parametric Solid Modeling (NX)



Essentials of Parametric Solid Modeling (SW)



MBD in the Product Lifecycle



Professional Certificates

PLM Certificate

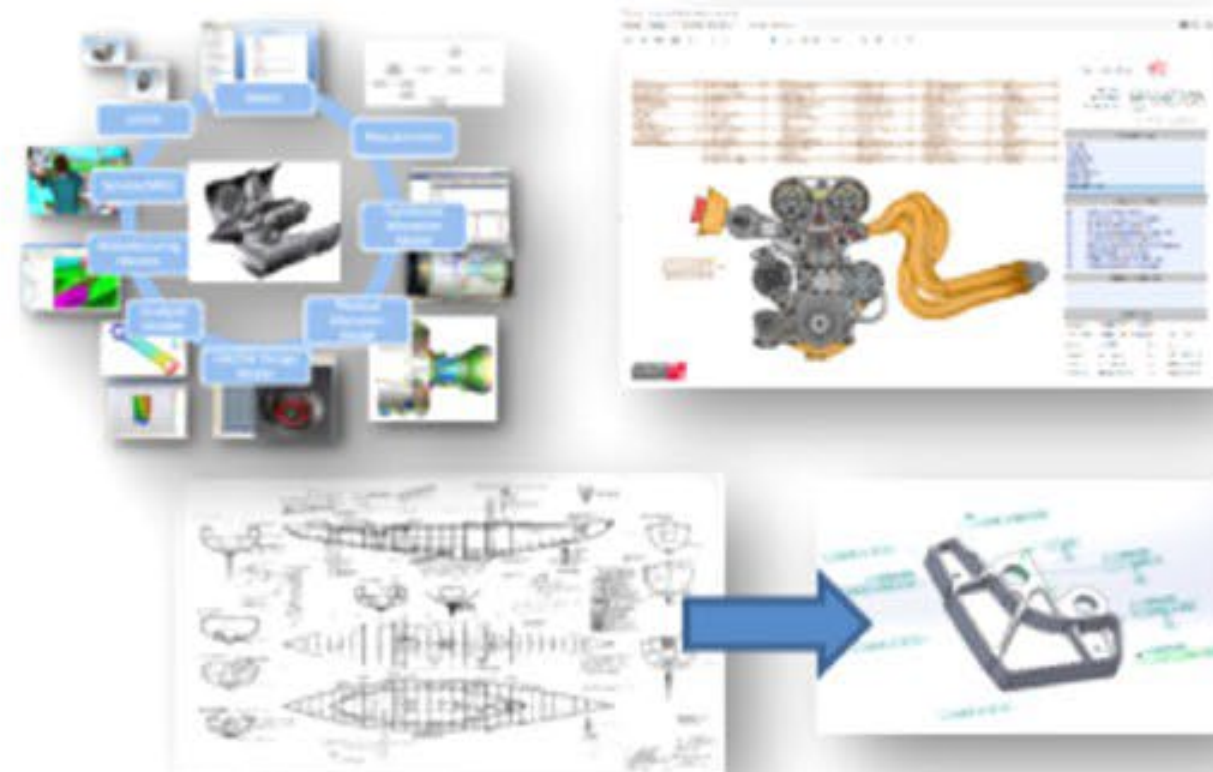
1. Digital Product Definition in PLM Environments
2. Product Data and Configuration Management in PLM Environments
3. PLM Across the Enterprise

MBD Certificate

1. Overview of MBD and PMI
2. Transformation from 2D to 3D Product Data
3. Model-based Data Exchange and Geometry Reuse
4. Guided Practice for Creating MBD

TDP Certificate

1. Introduction to Technical Data Packages
2. 3Di PDF TDP Background & Process
3. Guided Practice
4. The Future



<https://polytechnic.purdue.edu/digital-enterprise-center>

Educational Research

Research papers

- Fuerst, T., Zhou, J., Graton, S., Rudd, K., Camba, J.D. (2020). **A Case Study on Product Lifecycle Management in SAE (Society of Automotive Engineers) Collegiate Design Teams.** 2020 American Society for Engineering Education (ASEE) Annual Conference & Exposition, Montreal, Quebec, Canada, June 21-24.
- Astheimer, R., Fuerst, T., Camba, J.D. (2020). **Work-In-Progress: Product Data Management to Promote Higher Order Thinking.** IEEE Global Engineering Education Conference (EDUCON 2020). Porto, Portugal, April 27-30.
- Del Re, K. J., Yun, S., Kozikowski, E. J., Fuerst, T. & Camba, J. D. (2019), **Integrating a Product Life-Cycle Management System into a Freshman Level Classroom Environment.** 2019 American Society for Engineering Education (ASEE) Annual Conference & Exposition, Tampa, Florida, June 16-19.
- Mueller, A., Camba, J.D., Hartman, N., Fuerst, T. & Astheimer, R. (2019). **Development and Application of PDM Curriculum in Undergraduate Engineering and Technology Coursework.** 11th International Conference on Engineering and Computer Education, ICECE 2019. Guimarães, Portugal. September 8 -11.



Background

Education

- Successfully deployed Aras Innovator as a Learning Management System (LMS) in five engineering and technology courses at Purdue University (~1,300/semester).
- Design Build teams to implement PDM using Aras Innovator and Essig CAD Connectors and are supported by Digital Enterprise Systems & Tools Club (DSP&T).
- Partnerships with companies like CADENA PART Solutions, ANARK, CAPVIDIDA, Hexagon, ITI, and CAPVIDIA to bring technologies into the classroom.



Educational Research



***Student Club
PDM Implementation
(Aras Innovator)***

Implement PLM disciplines into Purdue Clubs!

- Team size: ~6 Students
 - Recruiting in progress
- Majors
 - Digital Enterprise Systems
- Sub teams
 - Training
 - Support
 - Documentation
- *“Purdue students to preach the PLM process”*



Our First Semester

- Club initiation
 - Leadership Board
 - Constitution
 - SLA
- Integrated clubs into Aras
 - Enterprise Management
 - Compliance Management
 - Data & Process Integrity

Teams

Search Clear Simple Default * [Icons]

| Name | Description | Is System |
|----------------------|--------------|--------------------------|
| Lunabotics | | <input type="checkbox"/> |
| Product Team | Product Team | <input type="checkbox"/> |
| PSP Hybrids | | <input type="checkbox"/> |
| Quater Scale Tractor | | <input type="checkbox"/> |
| Railside Robotics | | <input type="checkbox"/> |
| Robomasters | | <input type="checkbox"/> |
| ROV | | <input type="checkbox"/> |

Next Steps...



Purdue Pullers - Quarter Scale Tractor



Background

- Team size: 10-15 Students
- Majors
 - Ag Engineering
 - Ag Systems Management
 - Design Systems Management
 - Digital Enterprise Systems
- Competition(s)
 - Three North America events held in June
- Goal
 - Design a tractor that can pull farthest while also being able to turn well, and not fall apart going over large bumps



Purdue Pullers - Quarter Scale Tractor



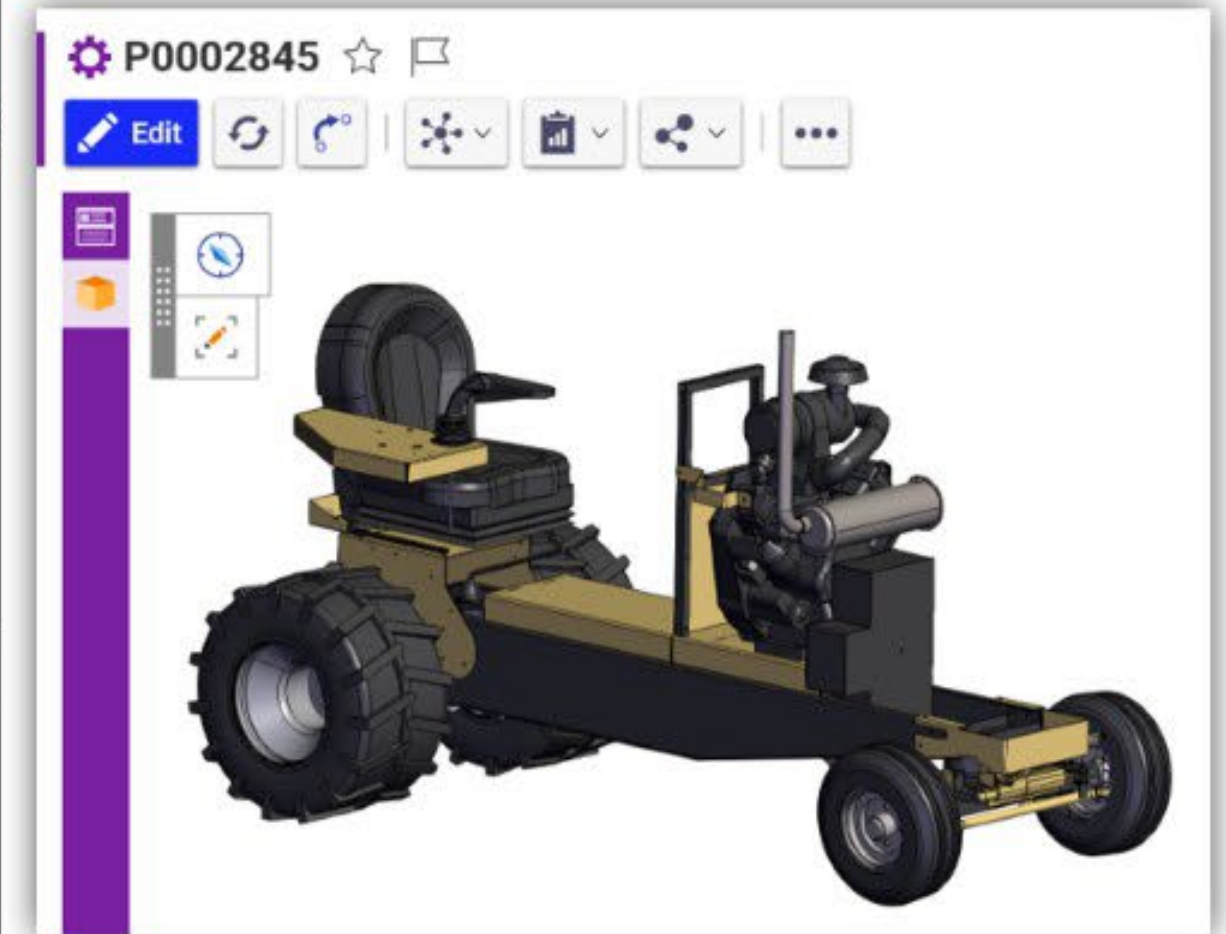
Product Data Management – Current State

The screenshot shows the Aras Innovator PDM software interface. At the top, the 'aras INNOVATOR' logo is visible. Below it, there are tabs for 'Parts', 'CAD-00003929', and 'P0002845'. The main content area displays the product details for 'P0002845', which is named 'Hammerdown 24'. The details include:

- Name: Hammerdown 24
- Type: Assembly
- Unit: EA
- Make / Buy: Make
- Cost: [blank]
- Effective Date: [blank]
- Long Description: Hammerdown 24 - The Tractor!

Below the details, there is a 'BOM' (Bill of Materials) section. It includes a table with the following data:

| Seq. | Assigned Cre... | Created By [...] | Part Number ↑ 2 | Revi... | Name | Description | Type | Quantity | State | Release Date ... | Unit | Referer |
|------|------------------|------------------|-----------------|---------|----------------------------|-------------|----------|----------|-------------|------------------|------|---------|
| 1 | Quarter Scale... | John Koellisch | P001273 | A | Cloud 9 Air Ride Front End | | Assembly | 1 | Preliminary | | EA | |
| 2 | Quarter Scale... | John Koellisch | P001276 | A | Torque Monster Drive Train | | Assembly | 1 | Preliminary | | EA | |
| 3 | Quarter Scale... | John Koellisch | P001278 | A | Pete Seat Operator Station | | Assembly | 1 | Preliminary | | EA | |
| 4 | Quarter Scale... | John Koellisch | P001279 | A | Electrical/Data Collection | | Assembly | 1 | Preliminary | | EA | |



Purdue Pullers - Quarter Scale Tractor



Experiences with Aras

- Ease of report making with cost calculation
- The learning process within the club had been slow
- Speed of Part finding and sharing files

Next Steps

- E-BOM
- CM2



Railside Robotics – Battlebots

Background

- Team size: ~30 Students
- Majors
 - STEM-focused
 - Open to all majors
- Competitions
 - Lots! (~1lb-3lb)
- Goals
 - We build battlebots!



Elmore Family School of Electrical
and Computer Engineering



Railside Robotics - Battlebots

aras INNOVATOR

Parts x P0001571 x P0001733 x

Parts Search Clear Simple Current Today Default

| Assigned Cre... | Created By [...] | Part Number ↑ | Revi... | Name | Description |
|-----------------------------------|---------------------------------|---------------|---------|------------------------------------|--|
| Railside R... | | | | | |
| Railside Robit... | Manan Singh | P0001553 | A | TDCZ-P-0100 Master Sketch | |
| Railside Robit... | Manan Singh | P0001556 | A | FHCS 4-20 X 0.5 LG Plastite | #4 1/2 flathead torx drive plastite screw M. |
| Railside Robit... | Manan Singh | P0001557 | A | BHCS 4-20 X 0.75 LG Plastite | #4 3/4" buttonhead torx drive plastite scre. |
| Railside Robit... | Manan Singh | P0001558 | A | Fingertech Mini BL-HELI 20A Bru... | Fingertech Mini BL-HELI 20A Brushless Sp. |
| Railside Robit... | Manan Singh | P0001560 | A | Malenki Nano | Malenki Nano https://itgres.com/product . |
| Railside Robit... | Manan Singh | P0001561 | A | Fingertech Mini Power Switch | Fingertech Mini Power Switch https://itgre . |
| Railside Robit... | Manan Singh | P0001562 | A | Fingertech F2822 Motor | Fingertech F2822 Motor https://www.fing... |
| Railside Robit... | Manan Singh | P0001569 | A | TEST-P-0201 Chassis | pdm testing model |
| Railside Robit... | Brandon Crud... | P0001570 | A | | |
| Railside Robit... | Owen Galvin | P0001571 | A | BACN-A-0000 TLA | Team Bacon Bad Top Level Assembly |
| Railside Robit... | Owen Galvin | P0001572 | A | BACN-P-0100 Master Sketch | Team Bacon Bad Master Sketch |
| Railside Robit... | Manan Singh | P0001724 | A | TEST-P-0301 Wheel | |
| Railside Robit... | Manan Singh | P0001725 | A | TEST-A-0000 TLA | |

Prev Next Page: 1 25

P0001739

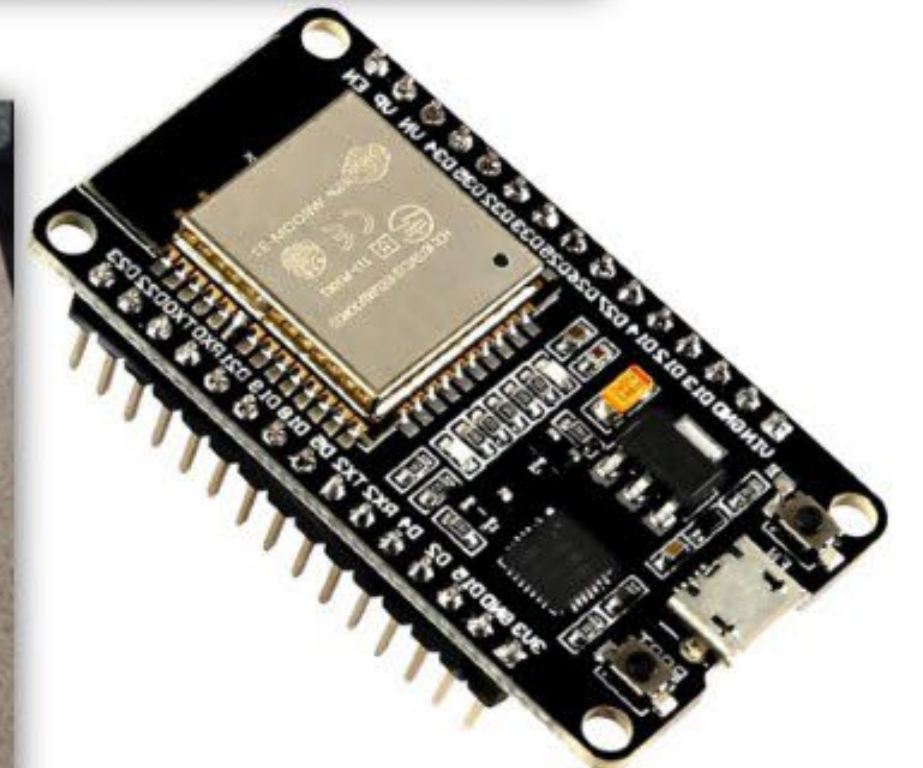


P0002522



Product Data Management – Process

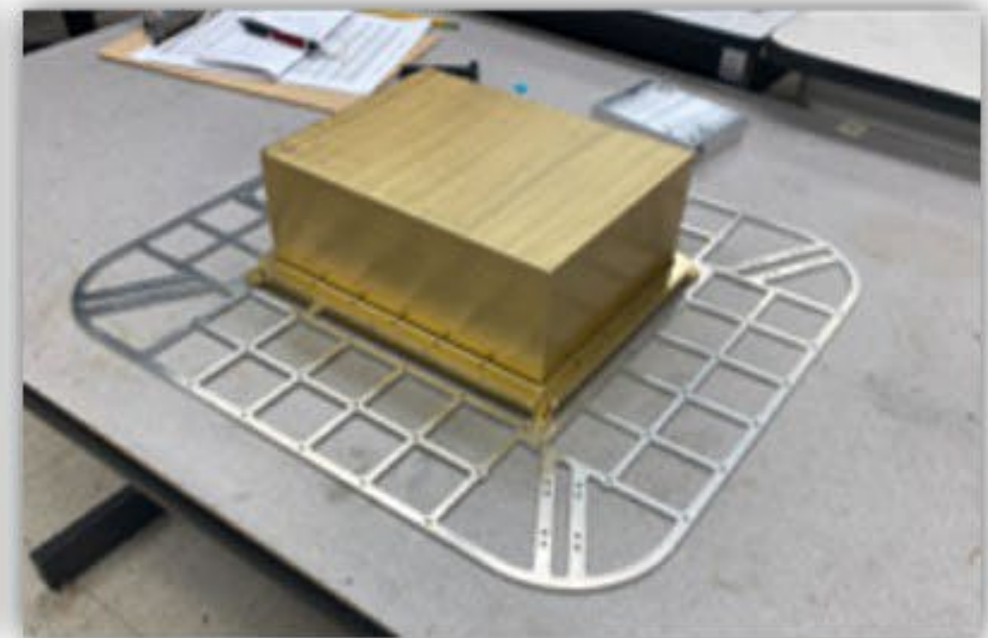
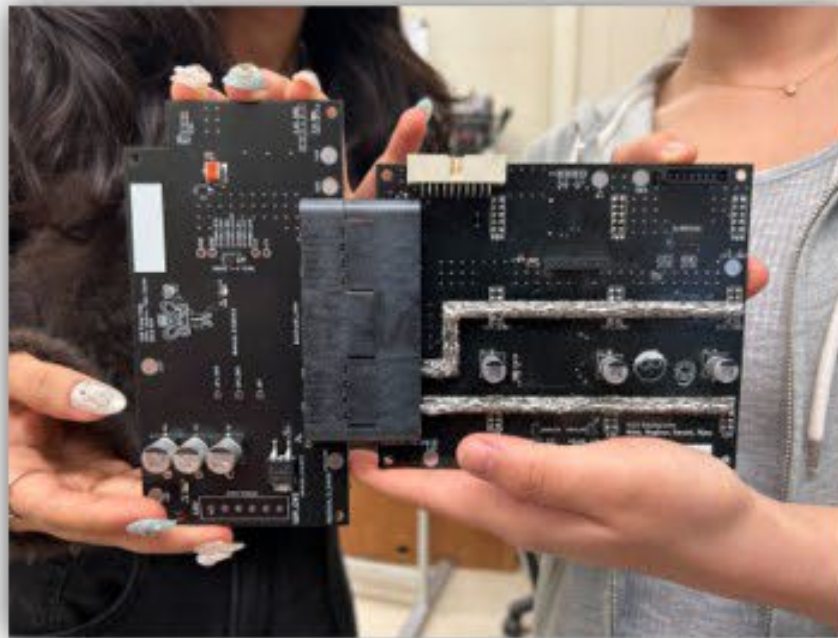
- Current State
 - All Standard/Custom models uploaded to Aras
 - Non-CAD files housed on Google Drive
- Next steps
 - Integrate design reviews with ARAS
 - Utilize product traceability alongside compliance management
 - Use Office Connector and mechatronics management



PURDUE IEEE ROV – Submarine Rover

Background

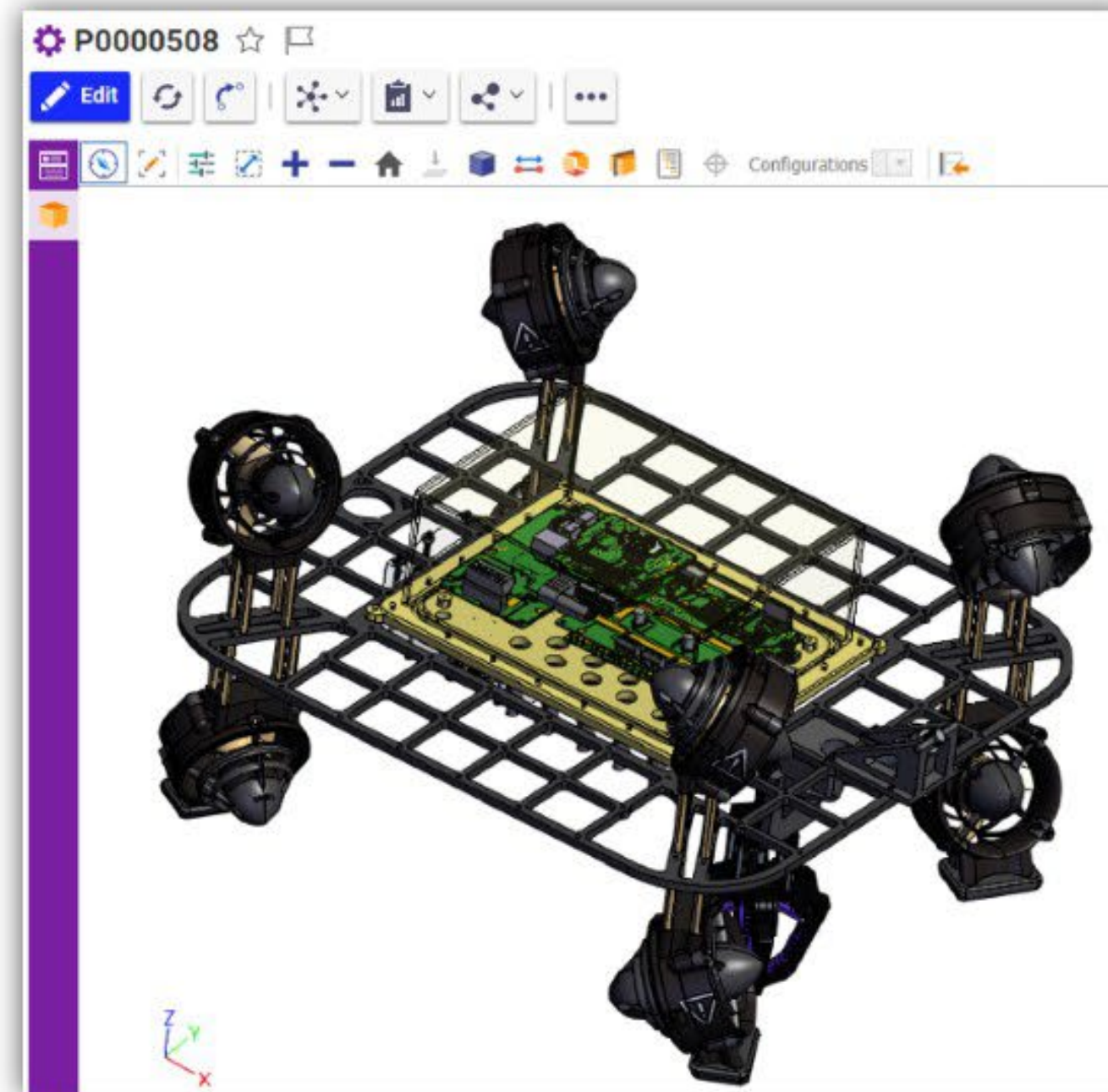
- Missions:
 - Win MATE ROV World Championship
 - To build up new engineers
- Team size: 45 Students
- Sub teams:
 - Mechanical Team
 - Electrical Team
 - Software team



ROV – Submarine Rover

Product Data Management – Current State

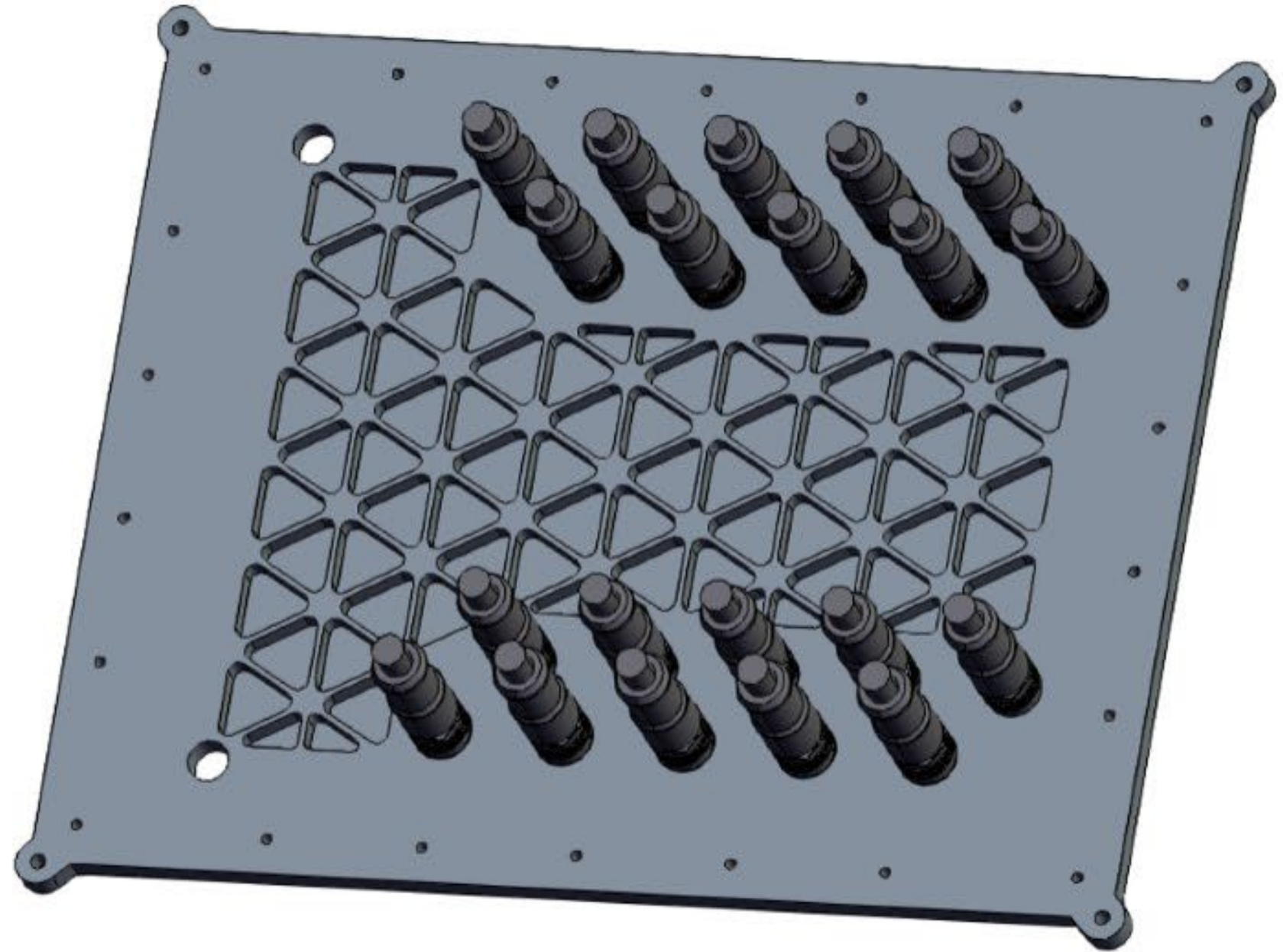
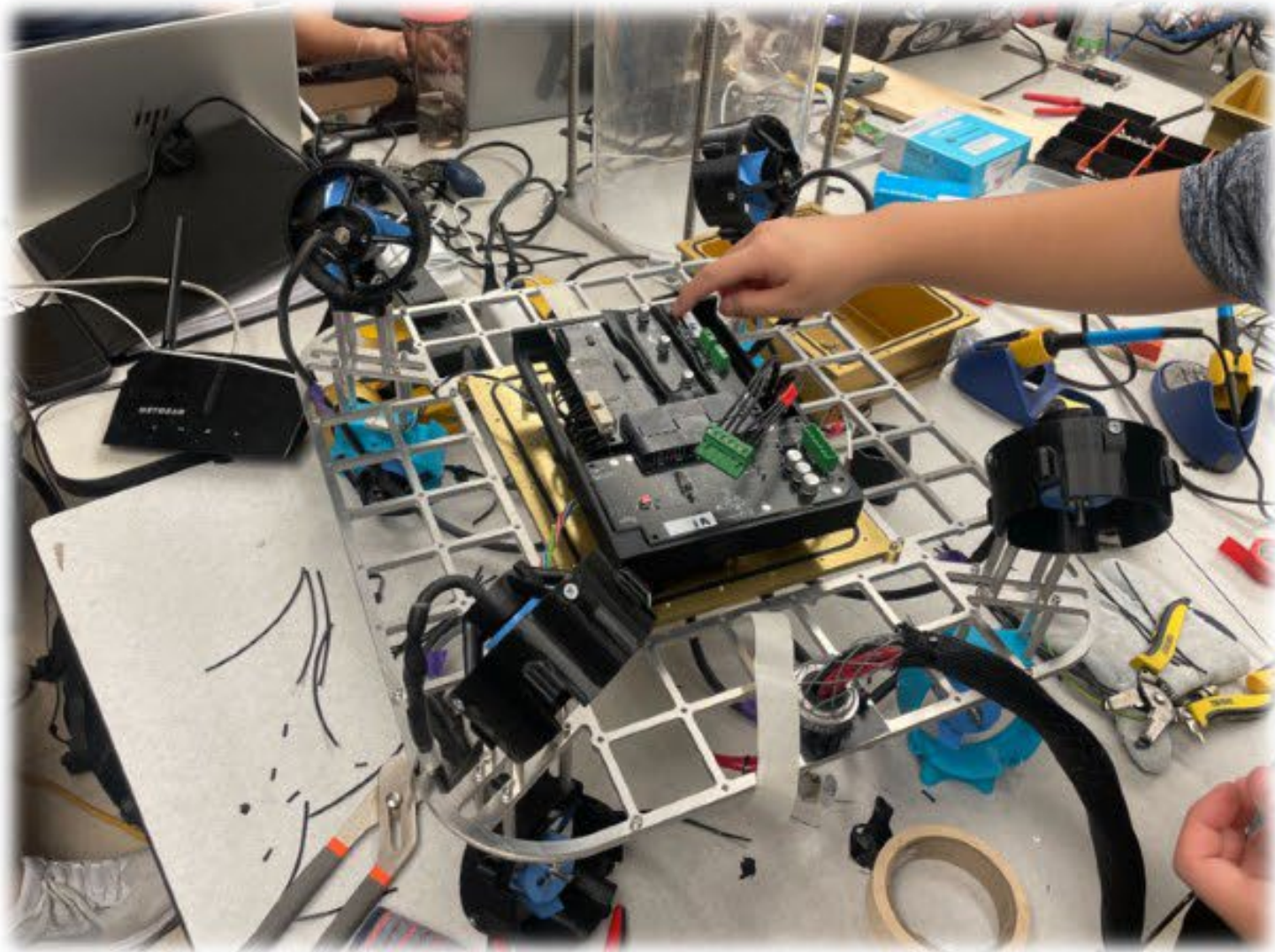
- Aras Innovator platform since November
- Less platform limitations
- Lots of growing pains
 - Transition year
 - Learning curve
 - Fighting for adoption



ROV – Submarine Rover

Our goals with Aras Innovator:

- Making Aras *easier to use*
- Improve Data Integrity
- Implementing change management



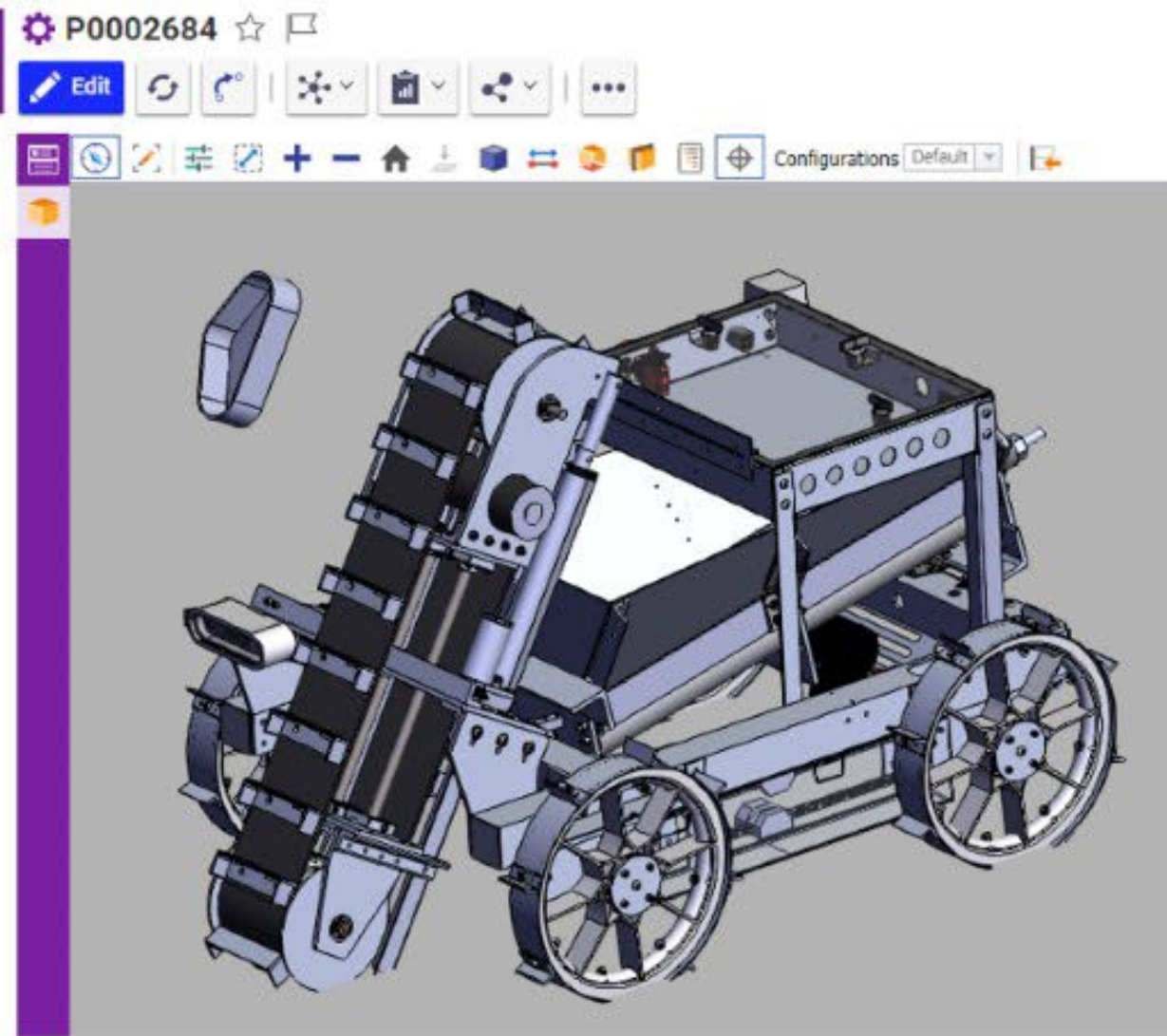
Purdue Lunabotics – Lunar Mining Robot

Background

- Team Size
 - 30 – 40 students
- Majors:
 - Engineering and Engineering Tech Majors
 - Computer Science
- Competition:
 - UCF Exolith Lab Qualifiers – May 11th – 14th
 - NASA Kennedy Space Center Finals – May 15th – 18th
- Goal
 - Design and Build an autonomous lunar construction rover



Purdue Lunabotics – Lunar Mining Robot



P0002684 ☆ 🚩

[Edit](#)
[Refresh](#)
[Undo](#)
[Share](#)
[Delete](#)
[More](#)

Part

Part Number: P0002684
Revision: A
State: Preliminary
Assigned Team: Lunabotics
Name:
Designated User: Lunabotics
Type: Assembly
Unit: EA
Make / Buy: Make
Cost:
Effective Date:

Long Description:

Changes Pending **Control Type:**

[BOM](#)
[BOM Structure](#)
[Alternates](#)
[AML](#)
[Documents](#)
[CAD Documents](#)
[Analysis Containers](#)
[Goals](#)
[Changes](#)
[Part Submission Warrants](#)
[Requirements](#)
[Requiremer](#)

Parts ☆

[Refresh](#)
[Settings](#)
[Search](#)
[Hidden](#)
[View](#)
[Share](#)

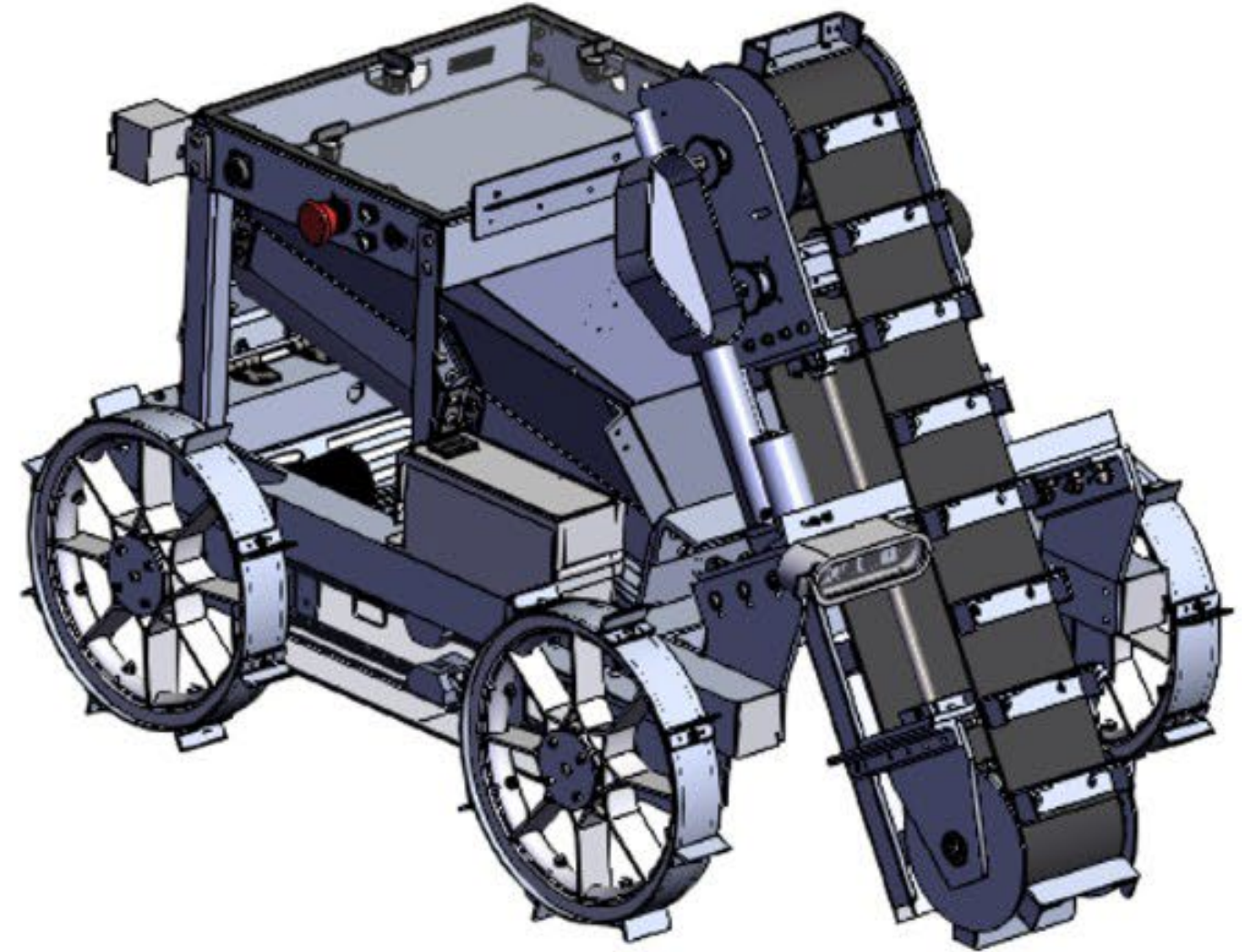
| Seq... | Assigned Cre... | Created By [...] | Part Number ↑2 | Revi... | Name | Description | Type | Quantity |
|--------|-----------------|------------------|----------------|---------|------------------|-------------|------------------|----------|
| 5 | Lunabotics | Nathan Stonit... | P0000789 | A | | | Assembly | 1 |
| 10 | Lunabotics | Kyle Delay | P0002685 | A | Sand*Render View | | Component/Com... | 1 |

[< Prev](#)
[Next >](#)
 Page: 1 of 1 | 2 Results |

Purdue Lunabotics – Lunar Mining Robot

Experiences with Aras

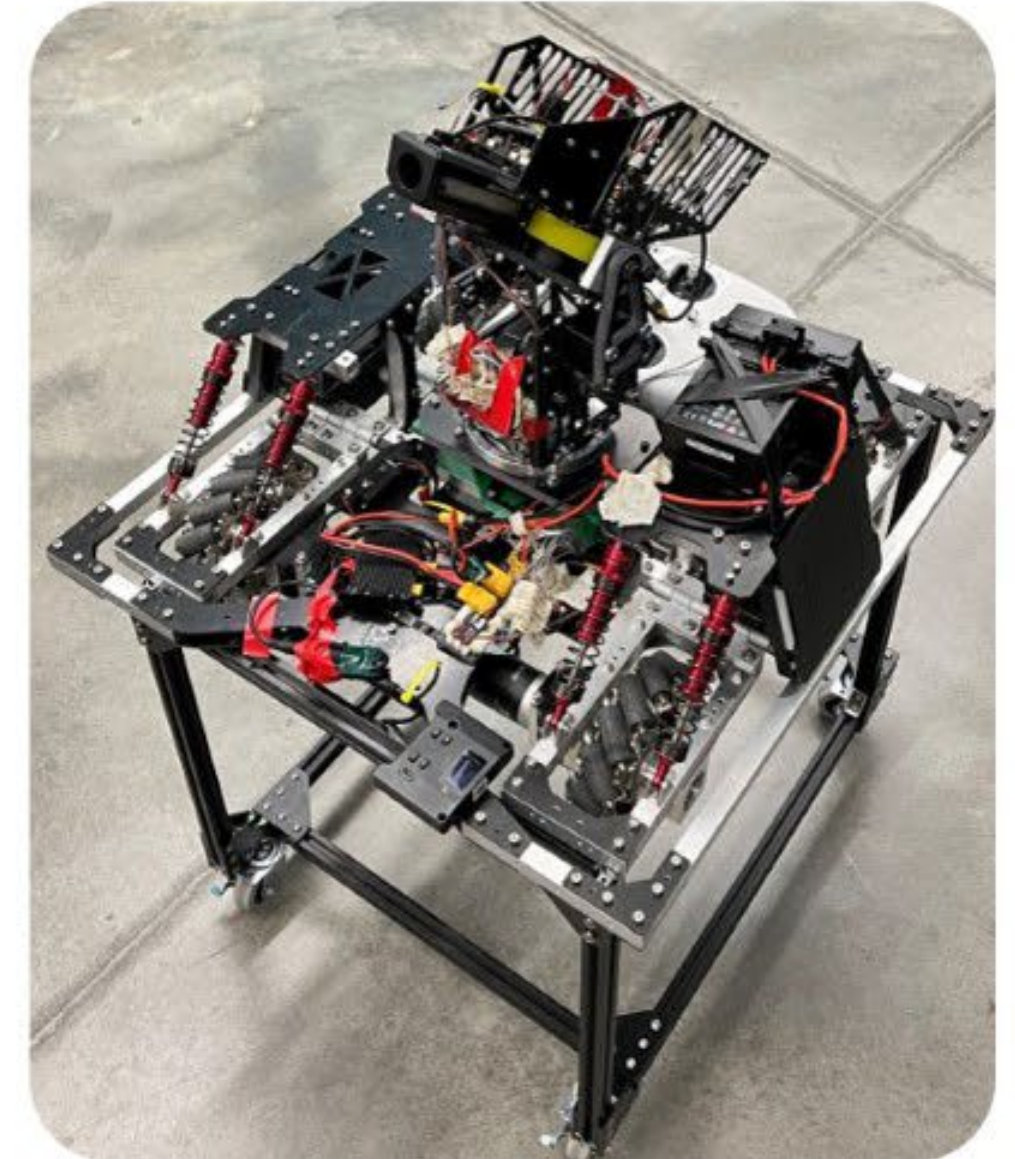
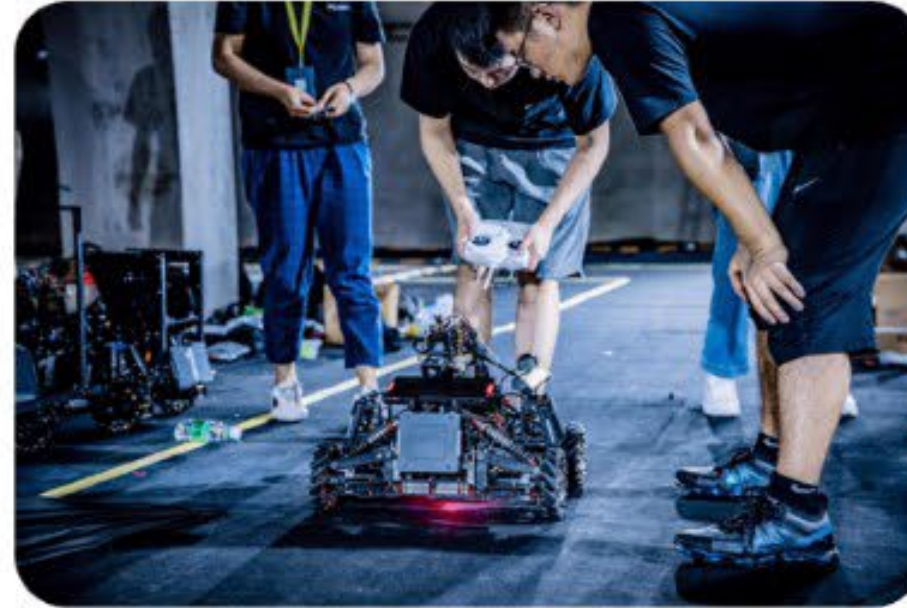
- Implement better workflows
- Next Steps
 - Legacy Data
 - E-BOM into ARAS
- Quote from Lunabotics Leadership:
 - "Aras has elevated our team's ability to professionally manage our extensive CAD models, facilitating more efficient collaboration and enhancing revision control"





Background

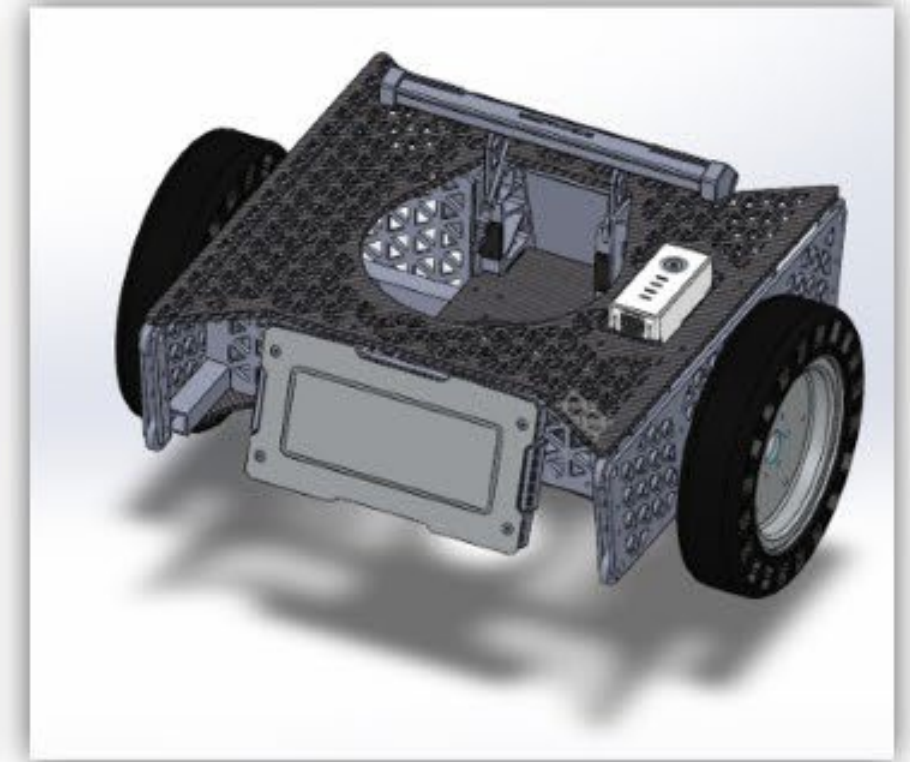
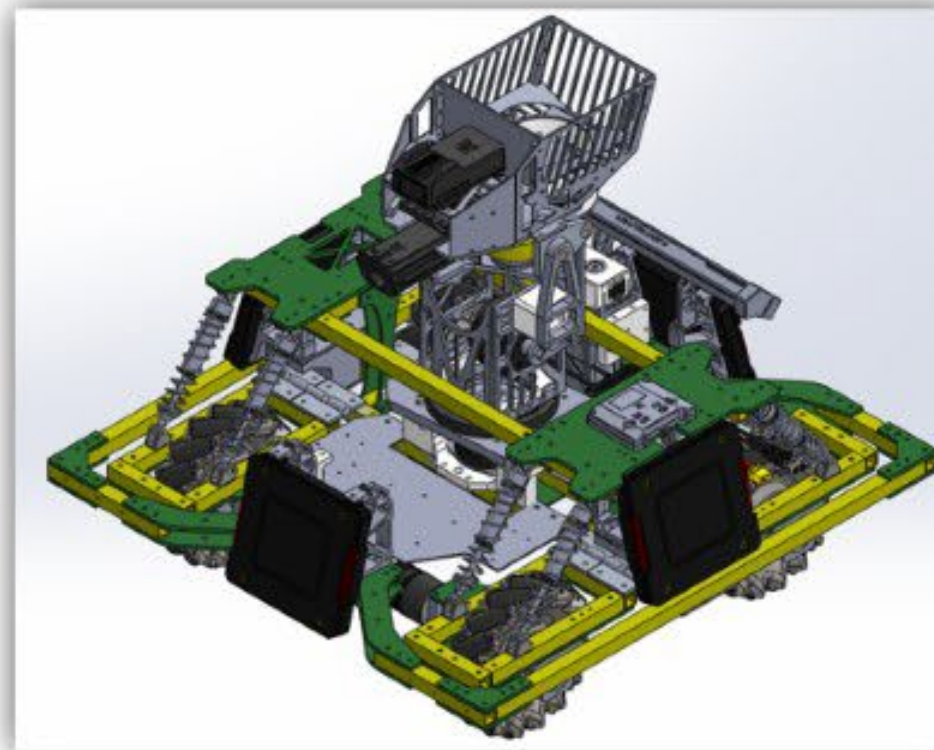
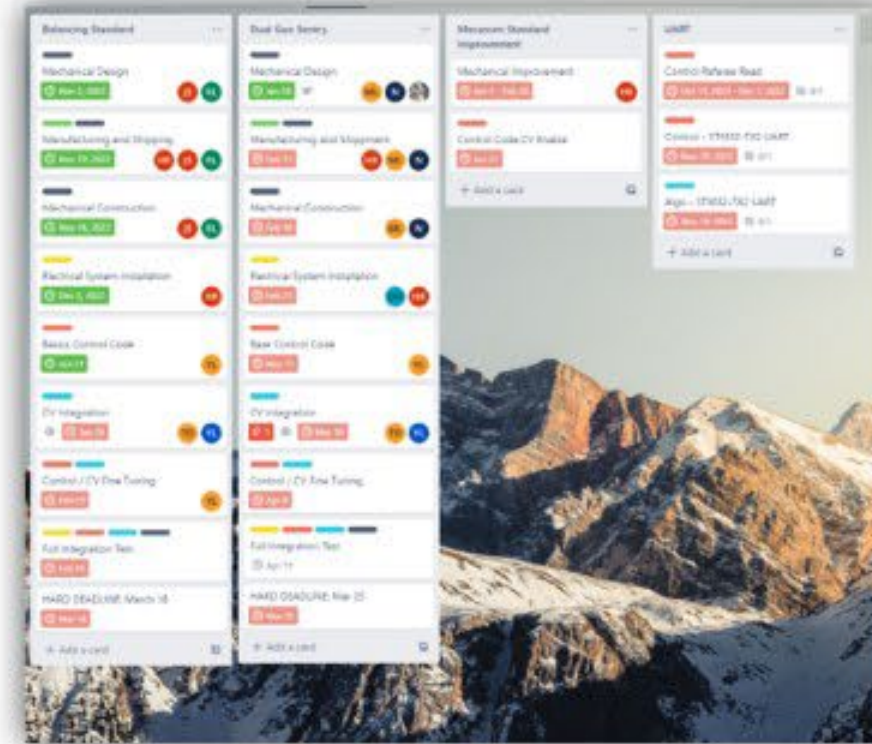
- Team Size: ~ 50 students
- Majors:
 - Engineering and Technology
 - Computer and Data Science
- Competitions
 - Midwest Conference
 - University League Competition
 - University Competition
- Goal
 - Passion for Robotics





Product Data Management – Current State

- Current State
 - Transitioning to ARAS from Google Drive, Onedrive and file servers
 - Project management via Trello
- Pain Points
 - Data scattered
 - Version control executed via Zip files
 - CAD dependency issues



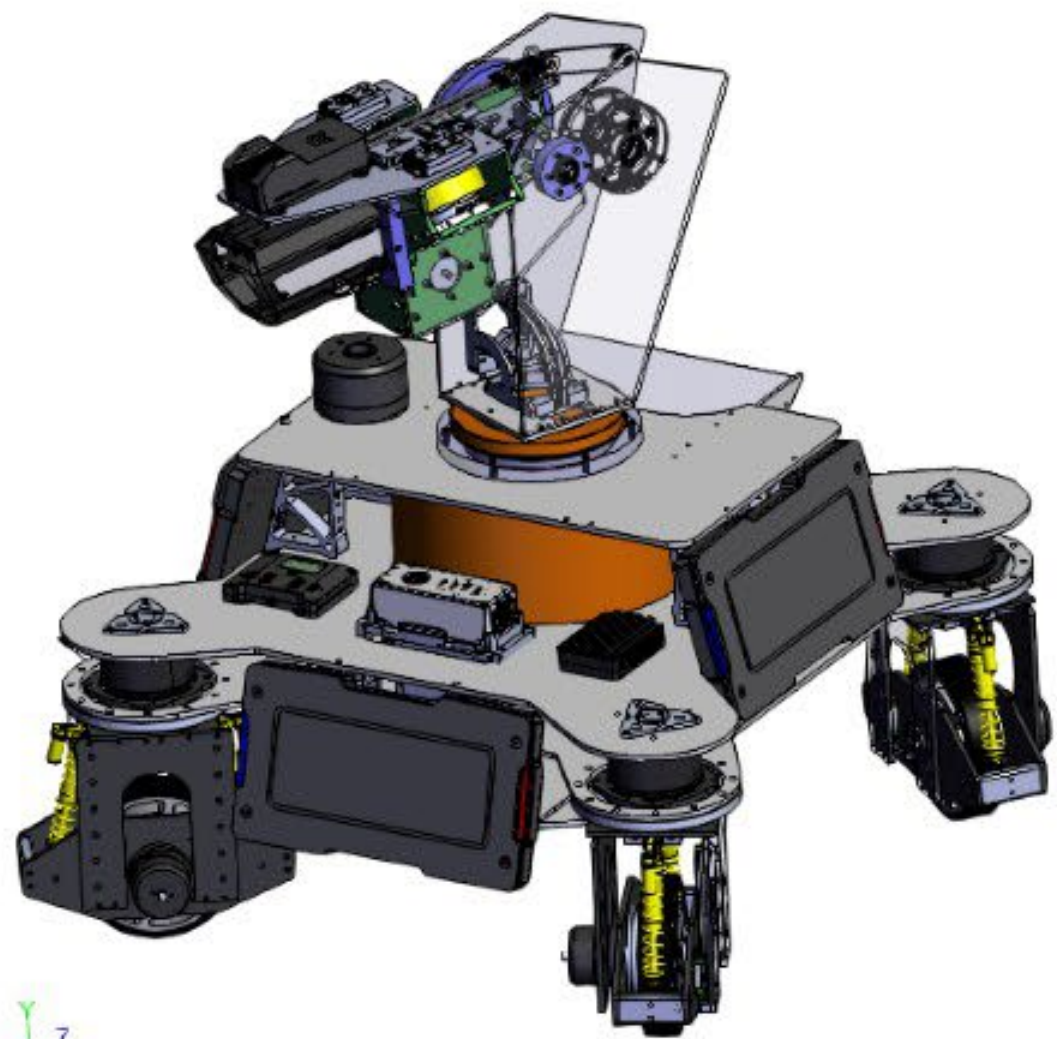
Purdue RoboMasters - BoilerBots



P0002291 ☆



Configurations Default



CAD-00003314 ☆



CAD Document

| | | | |
|-----------------|----------------|-------------|---|
| Document Number | Revision | State | Assigned Creator |
| CAD-00003314 | A | Preliminary | RoboMaster |
| Name | Hero_Robot | | |
| Type | Authoring Tool | Version | From Template |
| Assembly | SolidWorks | 2023_31 | |
| Description | | | |
| | | | <input type="checkbox"/> Changes Pending |
| | | | <input type="checkbox"/> Standard |
| | | | <input type="checkbox"/> Template |
| | | | <input checked="" type="checkbox"/> Dynamic Enabled |
| | | | <input type="checkbox"/> Streaming Enabled |

Native File
Viewable File

Structure Parents Files Changes Branch

CAD Documents

| Seque... | Assigned Creator... | Created By [...] | Document Nu... | Revi... | Name | Type | State | Native File [...] | Viewable File [...] | Authoring Tool | State |
|----------|---------------------|------------------|----------------|---------|-----------------------|--------------------|-------------|-------------------|---------------------|----------------|----------|
| 256 | RoboMaster | Jayson Stans... | CAD-00003182 | A | Chassis_Assembly_Hero | Mechanical/Asse... | Preliminary | CAD-000029... | CAD-000029... | SolidWorks | Prelimin |
| 384 | RoboMaster | Jayson Stans... | CAD-00003188 | A | Bumper | Mechanical/Part | Preliminary | CAD-000029... | CAD-000029... | SolidWorks | Prelimin |
| 128 | RoboMaster | Jayson Stans... | CAD-00003206 | A | Feeder_Assembly_Hero | Mechanical/Asse... | Preliminary | CAD-000029... | CAD-000029... | SolidWorks | Prelimin |
| 512 | RoboMaster | Jayson Stans... | CAD-00003320 | A | Gimbal_Hero | Mechanical/Asse... | Preliminary | CAD-000033... | CAD-000033... | SolidWorks | Prelimin |

Page: 1 of 1 4 Results

Purdue Space Program Hybrids

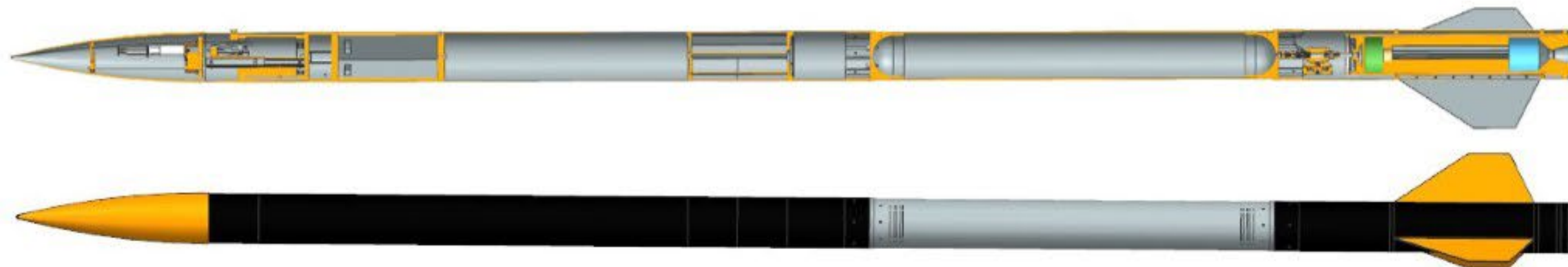
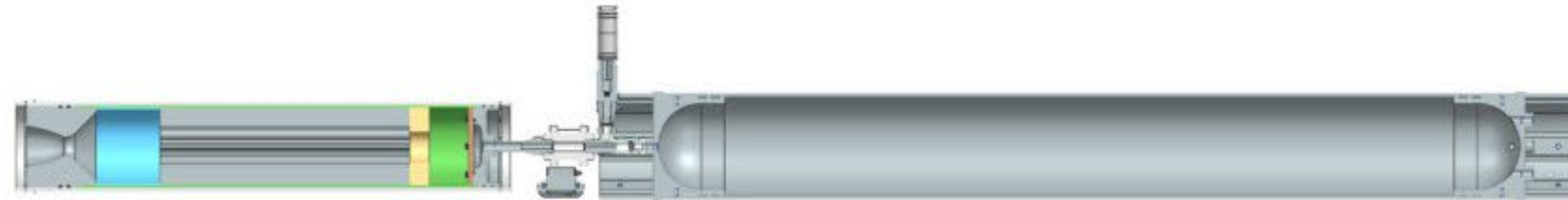
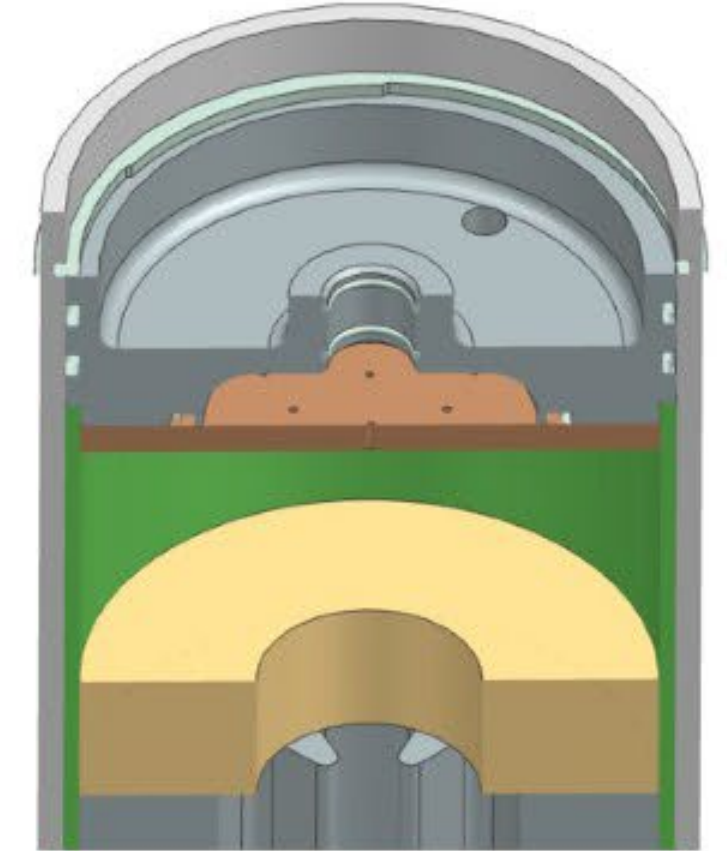
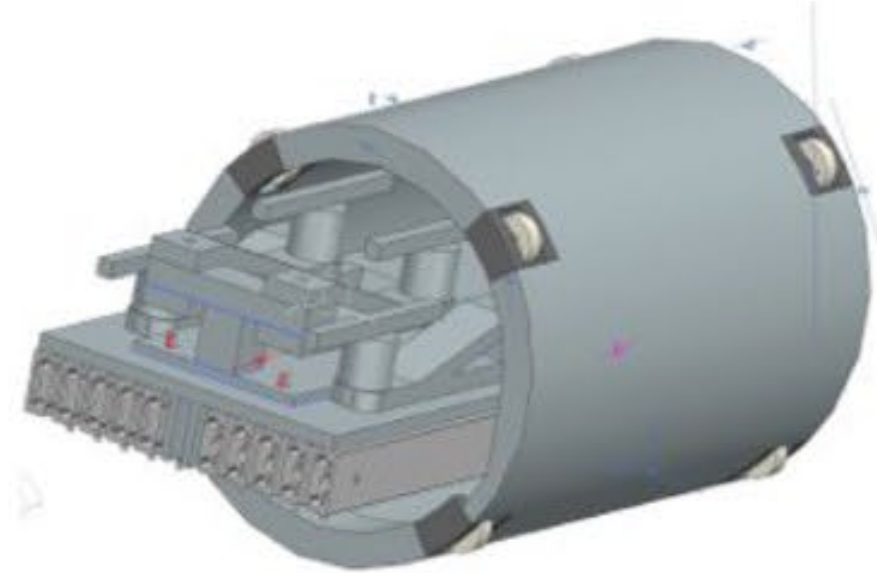
Background

- Team Size: 38 members
- Majors:
 - Engineering
- Competition
 - FAR 51025UNL, May 31st – June 2nd
 - Location: Mojave Desert, California
- Goals
 - To design, build and test experimental hybrid rockets
 - Experience



Product Data Management - Future

- Transitioning to ARAS
- Things that have benefited us:
 - Uncorrupted files
 - Streamlined data
 - Revision control





SAIC



 **Razorleaf**



Thank you for your time, and Boiler Up!

Any Questions?